The Features of the Coordinate Transformation from the Geodetic System WGS84 with the Mercator Projection for Low Latitudes Conditions Dr. Mohammad ABBOUD, Dr. Jad YOUNES, Eng. Hiba MOUSSA, Eng. Mohammad NASRULLAH

This work presents the computation procedures of a rectangular plan coordinates using data obtained through satellite observations when creating geodetic networks. The peculiarity of these works is in the coordinate conversion to the Mercator projection. The selection of the projection of coordinates is necessary for each condition, which significantly differs from a place to another in different localities on the surface of the Earth. When using the technology of global navigation satellite system, this task is relevant for any point (area) of the Earth due to a fundamental different approach in determining the coordinates. The fact that satellites determination is more precise than the ground coordination methods (i.e. triangulation). In addition, the conversion to the zonal coordinate system is associated with errors; the value at present can prove to be completely critical. Moreover, the conversion into zonal coordinate system is associated with errors, the value of which at present can prove to be completely curtail. The proposed methodology was conducted over the Lebanese territory. The expediency of using the Mercator projection in the topographic and geodetic works production at low latitudes is shown numerically on the basis of model calculations. To convert the coordinates from the geodetic system with the Mercator projection, a programming algorithm which is widely used in surveying has been adopted. Results showed that that the difference between coordinates in the proposed transformation method is within an order of 0.04 m. Accordingly, the modified algorithm can be successfully used to convert geodetic coordinates to plane rectangular coordinates.

Keywords: Geodetic network, scale factor, Algorithms, Lebanon

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INTRODUCTION

Usually, setting designs of any engineering work requires the utilization of rectangular plane coordinate system. Currently, its preparation is conveniently and effectively accomplished by the recalculation of geodetic coordinates. This is due to the rapid introduction into practice of geodetic works of satellite definitions. The coordinates of the points are obtained in the world geodetic coordinate system WGS-84 (GPS). Further, these coordinates are converted into a plane rectangular coordinate system. Thus, the general principle of the modern method of establishment of geodetic basic for the performance of construction works consists in determining geodetic coordinates using satellite receivers and transforming them into plane rectangular. In low latitudes, it is highly advisable to use the transverse Mercator projection [9].

METHODOLOGY

There are a number of algorithms used to transform from one coordinates system into another [1–8]. As part of these studies, the algorithm adopted in countries located in low latitudes [4-8] is considered, as well as the modified algorithm presented in [2, 3] for converting to the Mercator projection according to geodetic coordinates (ellipsoid WGS-84).

Briefly, we should note that in the system of plane rectangular coordinates in the Mercator projection, the X axis represents the equator is directed to the east, and the Y axis is the axial Meridian and directed to toward north. In this projection, the earth's surface is divided into three - and six-degree zones (discussed the six-degree zone). In the Mercator projection the first zone is that in which the axial meridian has a longitude of 177° (west).

Thus, for conditions of low latitudes when using global navigation satellite systems (GNSS) positioning needs a convenient, straightforward and effective method for converting geodetic coordinates to plane rectangular for specific engineering works. The task was to study the existing algorithms of coordinate transformation and to choose an effective conversion method. Below we show the well-known algorithms: given in [2, 3, 4–8], which can be called traditional. We Notice that the traditional method involves rather bulky formulas that are not

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convenient for automated calculations. The modified algorithm for low-latitude conditions is represented by more suitable for programming formulas.

Below, presented is the sequence of calculations using the traditional algorithm for low latitude conditions [4-8].

After determining the geodetic ellipsoidal coordinates (B, L) using the GNSS technology (coordinates on the WGS-84 ellipsoid) calculated are the plane rectangular coordinates (x, y) of the desired points in the Mercator projection.

1. Determine the zone number n by the longitude of the desired point:

$$n = TRUNC\left(\frac{L + L_{W0}}{6}\right),\tag{1}$$

Where, TRUNC – Truncates a number to an integer by removing the fractional part of the number; L – longitude of the point to be determined; L_{W0} – the longitude of the western boundary of the zone zero for the Mercator projection, $L_{W0} = 186^{\circ}$.

2. Determine the longitude of the Central Meridian L_0 of the zone n and the difference in longitude l at this point:

$$L_0 = 6 \cdot n - L_{C0}, \tag{2}$$

$$l = L - L_0, \tag{3}$$

Where, L_{C0} – the longitude of the Central Meridian of the zero zone for the Mercator projection, $L_{C0} = 183^{\circ}$.

3. Determine the eccentricity of the ellipsoid WGS-84

$$e = \sqrt{1 - \frac{b^2}{a^2}},\tag{4}$$

Where, a, b – respectively, the major and the minor semi-axes of the WGS-84 ellipsoid, a = 6378137 m, b = 6356752.3142 m.

4. Determine the Radius of curvature on the plane of the prime vertical:

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$$N = \frac{a}{\sqrt{1 - e^2 \cdot (\sin B)^2}},\tag{5}$$

Where, B – the latitude of the determined point

5. Determine the True distance along central meridian from the equator to the latitude (across from the point):

$$X = a \cdot [G_0 \cdot B - G_1 \cdot \sin(2B) + G_2 \cdot \sin(4B) - G_3 \cdot \sin(6B)], \tag{6}$$

Where, G_0 , G_1 , G_2 , G_3 -coefficients determined by formulas:

$$G_{0} = 1 - \frac{1}{4}e^{2} - \frac{3}{64}e^{4} - \frac{5}{256}e^{6}$$

$$G_{1} = \frac{3}{8}e^{2} + \frac{3}{32}e^{4} + \frac{45}{1024}e^{6}$$

$$G_{2} = \frac{15}{256}e^{4} + \frac{45}{1024}e^{6}$$

$$G_{3} = \frac{35}{3072}e^{6}$$
(7)

6. Determine plane rectangular coordinates (x, y) in the Mercator projection:

$$x = F_e + A \cdot N \cdot K_0 \cdot \left[\frac{1 + \frac{A^2}{6} \cdot (1 - T + C) + \frac{A^4}{120} \cdot \left(5 - 18 \cdot T + T^2 + 72 \cdot C - 58 \cdot \left(\frac{e^2}{1 - e^2} \right) \right) \right], \quad (8)$$

$$y = K_0 \cdot \left[X + \frac{l^2 \cdot N \cdot \cos B \cdot \sin B}{2} \cdot \left[\frac{1 + \frac{A^2}{12} \cdot (5 - T + 9 \cdot C + 4 \cdot C^2) + \frac{A^4}{360} \cdot \left(61 - 58 \cdot T + T^2 - 330 \cdot \left(\frac{e^2}{1 - e^2} \right) \right) \right] \right], \quad (9)$$

Where, F_e – false easting, equal 500000 m.

 K_0 – scale factor at the central meridian, equal 0.9996;

Coefficients A, C, T determined by formulas:

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$$\begin{bmatrix} A = l \cdot \cos B \\ C = \frac{e^2 \cdot (\cos B)^2}{1 - e^2} \\ T = (tgB)^2 \end{bmatrix},$$
(10)

Now formulas for the modified algorithm for low-latitude conditions [2, 3] shown in (table.1). Note the differences in formulas comparing with the traditional methods of coordinate transformation.

| $x = Fe + \frac{k_0 \cdot N}{\sqrt{V}} \cdot \operatorname{arth}\left(\sqrt{V} \cdot \cos B \cdot \sin l\right)$ | | | | | | |
|---|--|--|--|--|--|--|
| $y = Y + \Delta y$ | | | | | | |
| $Y = \frac{\operatorname{Re} \cdot k_0}{\rho} \operatorname{arctg} \left[\frac{\operatorname{Re} \cdot \sqrt{1 - e^2}}{a} \cos\left(\frac{\cos B}{6}\right) tgB \right]$ | | | | | | |
| $\Delta y = \frac{N}{\rho} \cdot \left[\operatorname{arctg}\left(\frac{tgB}{\cos l}\right) - B \right] / t$ | | | | | | |
| $\operatorname{Re} = \frac{3}{4}(a+b) - \frac{1}{2}\sqrt{a \cdot b}$ | | | | | | |
| $q = \cos(0,003 \cdot \sin 2B)$ | | | | | | |
| $N = \frac{a}{\sqrt{1 - e^2 (\sin B)^2}}$ | | | | | | |
| $t = 1 + 0,00084 \cdot (\cos B)^4$ | | | | | | |
| $V = \sqrt{1 + \left(\frac{e^2}{1 - e^2}\right) \cdot (\cos B)^2}$ | | | | | | |

Table 1: Modified algorithm for low-latitude conditions (Ellipsoid WGS-84)

Re-Equivalent Earth Radius

q – Isometric latitude

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FIG Working Week 2019 Geospatial information for a smarter life and environmental resilience Hanoi, Vietnam, April 22–26, 2019 t – Correction factor to ensure millimeter accuracy

V – Basic spheroidal formula

RESULTS

Accordingly, a comparison between the transformation results of geodetic coordinates obtained by using satellite observation at points of the geodetic network in Lebanon into plane rectangular in the Mercator projection (WGS-84 ellipsoid) between the modified algorithm and the traditional method of coordinate conversion are shown in Table 2.

| Table 2: Results of the transformation of geodetic coordinates (B, L, ellipsoid WGS-84) into |
|--|
| plane rectangular coordinates (x, y) in the Mercator projection |

| Geodetic coordinates | | Traditional algorithm | | Modified algorithm | |
|----------------------|-----------------|-----------------------|-------------|--------------------|-------------|
| В | L | <i>x</i> , m | y, m | <i>x</i> , m | y, m |
| 33° 06' 53.640" | 35° 24' 58.680" | 725454.800 | 3666623.016 | 725454.800 | 3666622.979 |
| 33° 09' 10.080" | 35° 15' 35.640" | 710767.932 | 3670500.440 | 710767.932 | 3670500.411 |
| 33° 20' 15.000" | 35° 18' 12.960" | 714392.733 | 3691072.589 | 714392.733 | 3691072.566 |
| 33° 14' 51.360" | 35° 30' 20.520" | 733445.984 | 3681536.176 | 733445.984 | 3681536.141 |
| 33° 22' 22.440" | 35° 45' 14.400" | 756218.787 | 3696016.783 | 756218.787 | 3696016.743 |
| 33° 26' 13.920" | 35° 33' 12.240" | 737375.735 | 3702672.400 | 737375.735 | 3702672.374 |
| 33° 29' 47.400" | 35° 23' 25.800" | 722076.805 | 3708888.827 | 722076.805 | 3708888.809 |
| 33° 39' 02.520" | 35° 29' 00.960" | 730317.636 | 3726194.521 | 730317.636 | 3726194.508 |
| 33° 34' 44.400" | 35° 40' 47.280" | 748723.365 | 3718696.404 | 748723.366 | 3718696.381 |
| 33° 30' 42.120" | 35° 53' 09.240" | 768066.424 | 3711745.593 | 768066.424 | 3711745.557 |
| 33° 39' 42.120" | 35° 52' 57.720" | 767305.582 | 3728376.137 | 767305.582 | 3728376.112 |
| 33° 47' 31.920" | 35° 31' 59.880" | 734542.254 | 3742000.893 | 734542.254 | 3742000.887 |
| 33° 55' 28.200" | 35° 39' 29.160" | 745720.228 | 3756967.166 | 745720.229 | 3756967.165 |
| 33° 47' 27.600" | 35° 59' 03.120" | 776305.504 | 3742986.963 | 776305.504 | 3742986.944 |
| 34° 00' 57.960" | 35° 44' 35.520" | 244518.560 | 3751508.324 | 244518.559 | 3751508.317 |
| 34° 11' 26.160" | 35° 44' 21.480" | 224641.158 | 3759646.752 | 224641.158 | 3759646.744 |
| 34° 12' 27.720" | 35° 58' 40.800" | 753317.260 | 3767335.110 | 753317.260 | 3767335.112 |
| 34° 19' 17.040" | 35° 48' 03.960" | 752437.731 | 3786682.274 | 752437.732 | 3786682.288 |
| 34° 26' 55.680" | 35° 57' 29.160" | 225359.641 | 3775758.310 | 225359.641 | 3775758.313 |
| 33° 52' 22.800" | 36° 14' 16.800" | 250687.907 | 3767439.505 | 250687.907 | 3767439.509 |
| 33° 56' 28.680" | 36° 01' 14.880" | 262960.887 | 3776957.496 | 262960.887 | 3776957.506 |
| 34° 05' 11.760" | 36° 01' 24.600" | 244478.734 | 3783879.388 | 244478.734 | 3783879.400 |
| 34° 01' 04.800" | 36° 18' 00.360" | 774386.503 | 3789196.755 | 774386.503 | 3789196.767 |

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| 34° 23' 20.400" 34° 26' 04.560" | 36° 22' 33.240" 36° 07' 45.480" | 236214.689 771772.909 | 3814083.865 3815890.480 | 236214.689 771772.909 | 3814083.895 3815890.511 |
|------------------------------------|------------------------------------|--------------------------|----------------------------|--------------------------|----------------------------|
| 34° 34' 31.440" | 36° 05' 25.440" | 233088.840 | 3829806.121 | 233088.839 | 3829806.161 |
| 34° 28' 35.040" | 36° 14' 29.040" | 246644.787 | 3818434.406 | 246644.787 | 3818434.439 |
| 34° 35' 51.720" | 36° 19' 47.640" | 255130.738 | 3831672.156 | 255130.737 | 3831672.196 |

When comparing the computed plane rectangular coordinates by two different methods for points distributed on the Lebanese territories, it is obvious that the difference between the coordinates is within the range of 0.04 m. Thus, it is shown that the modified algorithm can be successfully used to convert geodetic coordinates obtained by GNSS technology, WGS-84 ellipsoid and Mercator projection to plane rectangular coordinates.

Currently, the proposed algorithm is developed mainly to stimulate further research in this direction for all zones of the earth's surface.

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