

# MODERN SURVEY OF LARGE BRIDGE AND TUNNEL PROJECT FOR THEIR CONSTRUCTION CONTROL

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**Key words:** modern surveying technology, strait cross bridge, integrated marine survey system, ultrasonic wave, laser oscillator, trilateration net, VLBI & GPS, Radio Isotope Sensor

## ABSTRACT

Japan consists of four islands and many smaller islands. There are several projects connecting these islands, some are completed and some are under construction.

This paper introduces two topics, one is concerning the Akashi Brides project and the other is Tokyo Bay Cross Highway. The latter, Tokyo Bay Highway has been completed in Dec. 18, 1997 and the former, the Akashi Bridge completed in April 5, 1998. These have been dubbed the last country's giant public works of the last century.

These projects have both extensively used the modern surveying techniques for their construction. This paper outlines the surveying methodology that has contributed to the completion of these huge projects.

## 1. INTRODUCTION

Japan is situated on the East end of Asia and facing towards The Pacific Ocean and it extends about 3,000 km length. Japan has three to four thousand islands. There are four big islands, Honsyu (main island) which contain big cities like Tokyo and Osaka, Hokkaido, Shikoku and Kyushu where are the most attractive districts in politics, economics and industrial fields. These four islands are connected by bridges and tunnels which are national projects. They are The Seikann Tunnel (sea-bed tunnel of 23km between Hokkaido and the main island), Kanmon Bridge (712m between Kyushu and the main island) and they are already completed.

Akashi Strait Cross Bridge had been under construction between Honshu and Shikoku since 1986 and completed in 1998. It is for auto-use only, with six lanes of pavement. This is one of three routes connecting The Main island and Shikoku. They lie in The Inland Sea with in abundant of beautiful natural scenery, one part of the Japanese National Marine Park.

The other main topic will describe the 15.1 kilometres Tokyo Bay Cross Highway (we call it Aqua line), that consists of an approximately 10.1km long shield tunnel portion from Kawasaki and a bridge portion about 5km from Kisarazu with a man made island linking the bridge and tunnel portion to the central tunnel.

These two big projects mentioned above, are extensively managed by the modern surveying technology in its process of construction. This report describes on how surveying technique was used and how this contributed to the actual field construction project.

## 2. AKASHI STRAIT CROSS BRIDGE

There are three routes connecting The Main island and Shikoku as I already mentioned above. The Akashi-Naruto route is one of them and completed in April of 1998. The Akashi Strait Cross Bridge is on the Akashi-Naruto route and is near to the main land and the longest suspension bridge in the world. The bridge's total length is 3,910 meters and consist of three spans with two hinge stiffening trusses. The construction charge is 4,013,235,000 \$ and 836,029,400\$ per 1km in 4,8km length including the bridge and the connecting part to the national highway. It is more expensive than the other bridges connecting between The Main island and Shikoku.

The allowable wind velocity for designing this bridge presumed to endure for the one occurring once during 150 years. The truss with stiffener girder type is maintained to keep safely at the time of 80m/sec heavy storm. The two cables with 1.1 meter diameter which consists of 37,000 piano metal lines, each line has 5 mm diameter, were used for supporting the stiffener girder truss load. The height of the main tower is about 300 meters above the mean sea level of Tokyo Bay. It exceeds the Tokyo Tower height of 333 meters by adding the foundation height. Fig. 1 shows the cross section of the bridge.

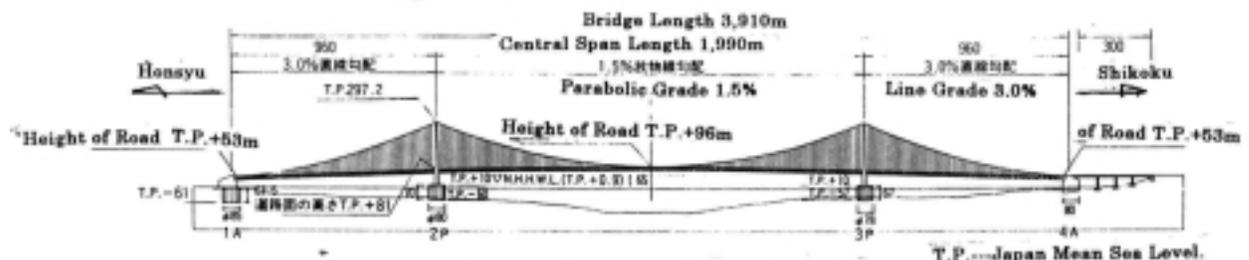


Fig.1 Akashi Strait Cross Bridge

Fig. 1. Akashi Strait Cross Bridge

### 2.1 Surveying of Akashi Strait Cross Bridge

Surveying of Akashi Strait Cross Bridge is divided into four categories, they are fundamental control surveying, surveying for setting the steel caisson foundation, control survey for main tower and cable of suspension bridge.

### 2.2 Fundamental Control Surveying

This is the control survey to determine the coordinates for field work of bridging and its related at both beach sides. This is the first and second order trilateration method using electromagnetic distance meter (EDM) and theodolite. Ten reading works in one set are continued three times and the allowable deviation of reading distance in one set is

within 20mm in consideration of all meteorological data. The difference between actual measured distance and checking survey is as follows:

**Table 1.** Distance Check (Spherical)

First Order Net

Ins.Pt.	Obs.Pt.	Length	Check	Dif.	Lim
AA I -2-1		3 896.738	3 896.752	+14	20
	AA I -5 長 坂	3 702.163	3 702.169	+ 6	
	AA II -16	※6 472.284	6 472.294	+10	

Second Order Net

Ins.Pt.	Obs.Pt.	Length	Check	Dif.	Lim
AA II -23	AA II -21	933.670	933.674	+ 4	20
	AA II -25	964.136	964.138	+ 2	

Fundamental control survey was performed using the Range-master-III type, YHP 3808A Wild T3 and T2. After 1963, K+E Auto-ranger-JX and Sokkia Total Station SET 2EX were used instead of Range-master. The result of over-sea levelling using Wild N3 and T3 is as follows:

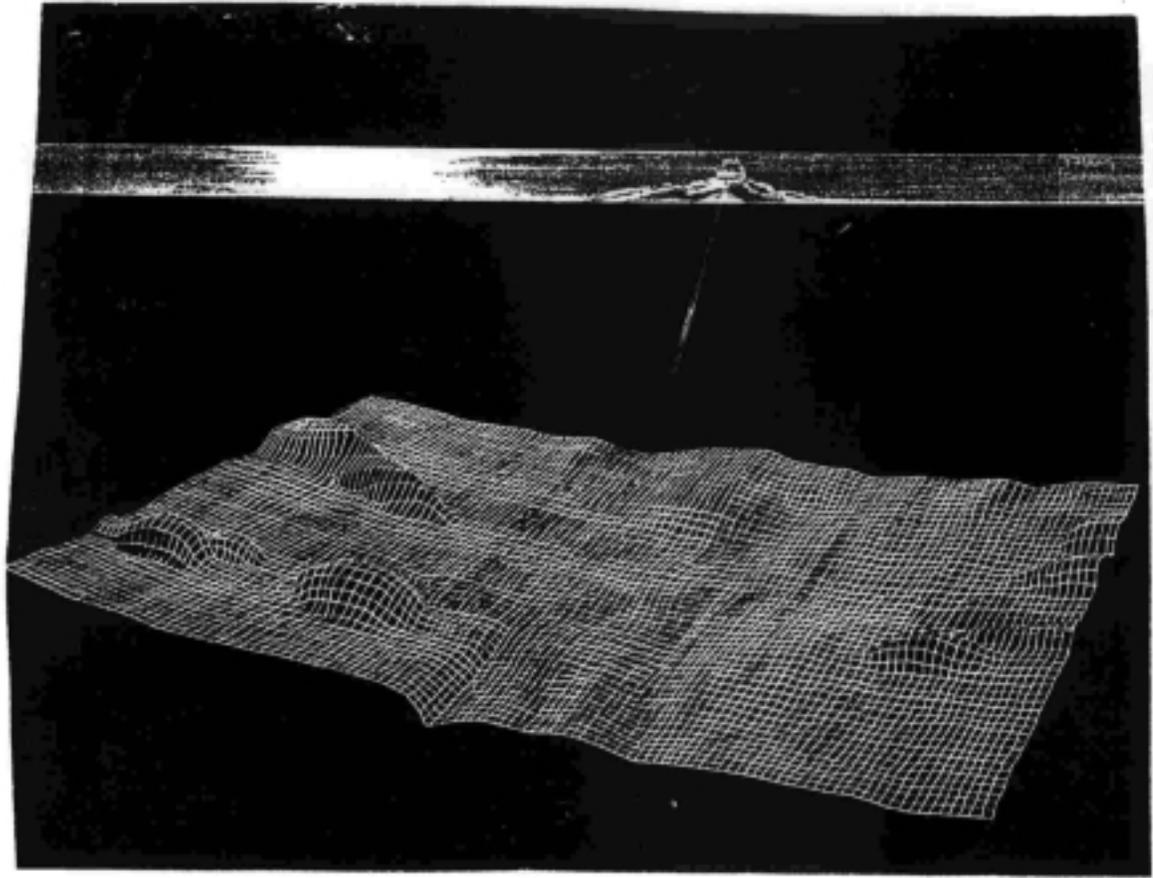
- The standard deviation of one observation value + 11.3mm
- The standard deviation of mean value + 1.9mm

At the both beaches the first order levelling was performed and the error was -0.6mm and

-0.7mm compared to the national levelling points.

### 2.3 Surveying of Steel Caisson Foundation

The Steel Caisson was set up at the predetermined position as the both pier foundation of 2P and 3P of the main tower. Before the setting the steel foundation, large-scale dredger was used for excavating works in accuracy of flatness within+20cm at the sea bottom of 60 meters deep. There at the sea-bottom, the integrated marine survey system was used to check the flatness of excavated bottom. This system measures various marine data such as marine current velocity, direction, temperature besides the depth of sea bottom. Such data are acquired in real time by using ultrasonic wave with topographic resolution +5cm. All types of marine information are recorded on one magnetic tape and on time computed. Unprecedented accuracy is achieved with frequency of 500 kHz and a resolving power of 5cm. Water depth is measured at 120 points in one second by scanning every 1/15,000 second. The figure shows the on-line measuring system by ultrasonic wave which are managed automatically by multi-fan beam modulator on the Grab Ship. The dredger can be used for excavating depending upon the result of sea-bed measurement by ultrasonic wave.



**Fig. 2** High Performance Three-Dimensional Sea bed measuring System developed by Taisei Construction Co. Ltd. Dr. Kanzaki.

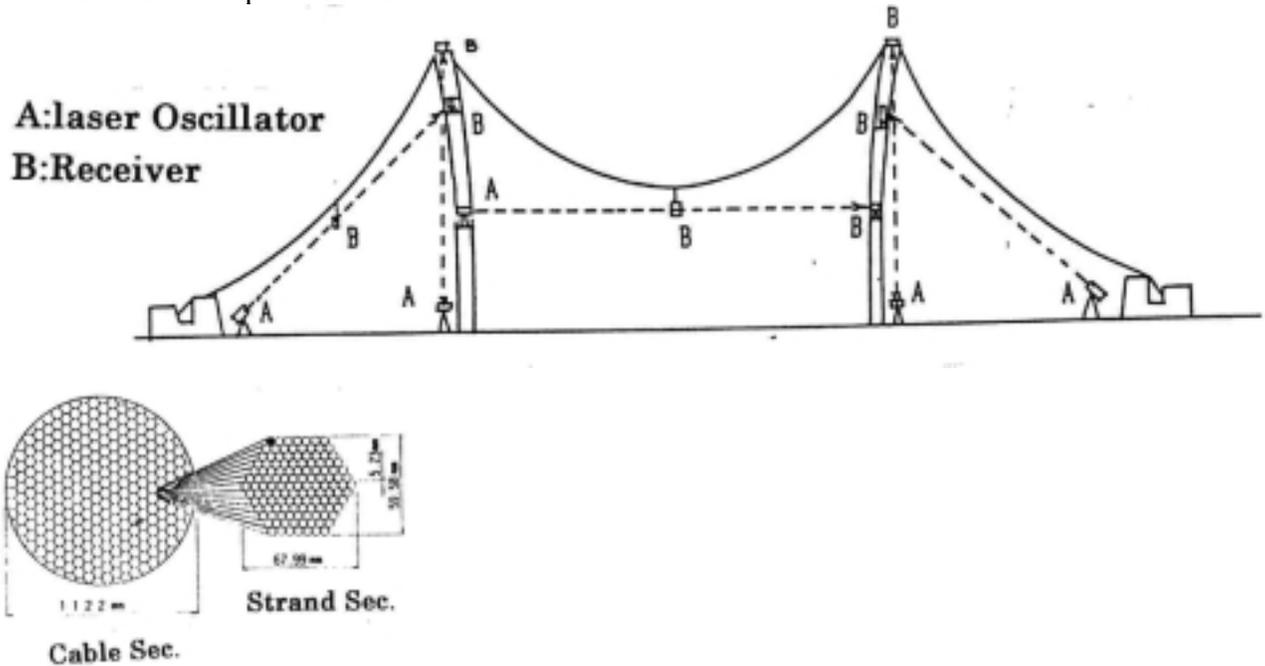
The three-dimensional topographic measuring system emits a fan-shaped beam of 500 kHz, called a multi-fan beam, and electronically scans by the cross-fan method to measure depth data at 120 points. Depth is measured every second by an electronic scanner and the moving vessel acquires three-dimensional information on the seabed in a short time.

- Unprecedented accuracy is achieved with frequency of 500 kHz and a resolving power of 5cm
- Higher frequency and compactness of the transmitter / receiver (30kg)
- Continuously measures the topography of the seabed at a width over three times the water depth.
- Water depth is measured at 120 points in one second by scanning every 1/15,000 second.
- Real-time data is acquired on board, with the resultant increase in work management efficiency.

## **2.4 Control Survey of Main Tower and Cable**

The control survey of the main tower has been done in the factory and checked in fabricating process each 30 step and used three dimensional comparator machine. The several points are checked as each scaffolding step whether the position accuracy is kept within 1/10,000 and finally at the top of the tower in the filed, accuracy of coordinates was controlled within 28.3mm. Also vertically was surveyed by EDM system. This operation was performed during midnight, sometimes continued up to the early morning and finally placed within 1/5,000 of the tower lenght at the top of tower. In fact the verticality error was +5.26mm in south direction and 0.06mm in east direction and 1.08mm as mean value in all direction and gained high accuracy result.

The control survey of cable was performed using laser oscillators when it hanged over the bridge. The figure shows the field works, A is laser oscillators and B is receiver. At the center of cable, the sag is adjusted so as to keep the predetermined value in consideration of temperature affection.



**Fig. 3** Control Survey of Cable

### 3. TOKYO BAY CROSS HIGHWAY (TOKYO BAY AQUA LINE)

The Trans-Tokyo Bay Highway completed on Dec. 18, 1997, after eight years four months. The project to build the 15.1 kilometer Tokyo Bay Aqua Line – a toll road that includes the tunnel and links Kawasaki and Kisarazu in Chiba Prefecture – cost 1.44 trillion yen (10.6 billion \$). The road consists of approximately a 10 km long shield tunnel portion from Kawasaki, a bridge portion is about 5 km long from Kisarazu with a man-made island linking the bridge and the tunnel portions to the central tunnel. This construction project is of a scale unequaled anywhere in the world requiring the introduction of the latest technology, from the design stage right through to the actual construction work.

Lower figures show the plan and profile of Trans-Tokyo Bay Highway.



### **3.3 Control Survey in Tunnel**

Control survey in tunnel was executed using the outer control points for construction of shield tunnel. The outer control points and inside control points in tunnel are connected by following two ways. The one is piano wire line points dropped into tunnel. The two points dropped in tunnel are extended by means of traversing survey with total station system. Concerning to the deviation of measuring values within tunnel, at the sites of 1,010m and 1,190m from entrance of tunnel, traversing points set on the upper half of tunnel section and lower part were compared to the coordinates and confirmed within +30mm and direction errors by Gyroscope were also checked within 5 second. At the joint point of excavating tunnel from both sides, the deviation error between Kawasaki man-made island to Ukishima (refer to Fig.4) was 151.4mm traversing points 26, mean length between points 81m, standard deviation of measuring angle +3.88" and from Ukishima to Kawasaki man-made island was 62.7mm, traversing points 13, mean length between points 258m and standard deviation of measuring angle +1.66".

### **3.4 Assembling accuracy of Segment**

To join the segment within the tunnel, excavating machines of both sides stops separating from each side 50 meter. The head of boring machine RI sensor (Radio Isotope) is attached to detect the positions in the tunnel section. The RI sensor can measure within +5mm in plane, therefore during excavation in 50 meter, segment of both side section can coincide within error of 1cm.

## **4. CONCLUSION**

Here the typical Japanese Civil Engineering Projects are introduced and how the modern survey technique has taken advantage of its process of construction. The author hopes to contribute these technology in more systematic, automatic and integrated way in conjunction to other high technology in all engineering fields in future. He also welcomes any comments and suggestions on this paper and its related problems.

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## **BIOGRAPHICAL NOTE**

**Taichi Oshima** got Dr. Eng. Degree from University of Tokyo and he had been engaging in research and teaching in University of Tokyo, Institute of Industrial Science for 26 years and Hosei University for 20 years. Besides that academic career, he had given lectures in several national and private universities. He has also involved in International Meeting and Symposium as a speaker and session chairman.

He was qualified as a professional licensed surveyor in 1967. He also joined to JSPRS (Japan Society for Photogrammetry and Remote Sensing) as a Secretary general for about 12 years from 1961 and contributed for bridging JSPRS to ISPRS (International Society of Photogrammetry and Remote Sensing) and contributed to organize the International Symposium of Comm. V of ISPRS in 1966. He firstly joined to the FIG Congress in London in 1964. He had contributed to join JFS (Japan Federation of Surveyors) to FIG. He was very active Commission activities in Commission 6. He worked as a Session Chairman and Working Group Member. He was a Secretary of Commission 6 from 1978 to 1984 for 6 years. He succeeded to organise FIG PC meeting in Tokyo 1985 firstly in Asia.

He has had many years of involvement in international activities, among them he joined as a member of the Research Mission of Indian Historical Monuments and important properties in Medieval times, dispatched from University of Tokyo from 1959 to 1961 to India and engaged in field works about one year and half. He was in charge of surveying measurement of many monuments and building and classified in chronological order. This research works had continued for about 20 years for completing the works including the field checking and published the research books, three volumes still now preparing the fourth book.

He has engaged in 180 projects, TC28, SC5 as a convener and chairman of Japanese Committee.

He has published 15 professional books and 150 papers.